

Application No. 10/065,866
Attorney Docket No. 129716
Amendment dated January 25, 2005
Reply to Office Action of November 26, 2004

AMENDMENTS TO THE CLAIMS

Please amend the claims as follows:

1. (Previously presented) A patient positioning system for medical applications, said system comprising:
 - a patient positioning surface for supporting a patient;
 - a lift subsystem for adjusting elevation of said patient positioning surface;
 - a longitudinal subsystem including a rack and pinion mechanism for moving said patient positioning surface in a longitudinal direction;
 - a lateral subsystem for moving said patient positioning surface in a lateral direction;
 - a tilt subsystem including a ball screw and rotary nut for tilting said patient positioning surface;
 - a rotation subsystem for rotating said patient positioning surface; and
 - a control subsystem for controlling operation of said patient positioning system.
2. (Original) The system of claim 1, wherein said control subsystem performs iso-center tracking to maintain a region of interest of said patient in an image area during tilt.

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3. (Previously presented) A patient positioning system for medical applications, said system comprising:

- a patient positioning surface for supporting a patient;
- a lift subsystem for adjusting elevation of said patient positioning surface;
- a longitudinal subsystem for moving said patient positioning surface in a longitudinal direction;
- a lateral subsystem for moving said patient positioning surface in a lateral direction;
- a tilt subsystem including a ball screw and rotary nut for tilting said patient positioning surface;
- a rotation subsystem for rotating said patient positioning surface; and
- a control subsystem for controlling operation of said patient positioning system,

wherein said lift subsystem adjusts elevation of said patient positioning surface using a two-stage synchronized telescopic lift system.

4. (Currently amended) A patient positioning system for medical applications, said system comprising:

- a patient positioning surface for supporting a patient;
- a lift subsystem for adjusting elevation of said patient positioning surface;

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a longitudinal subsystem for moving said patient positioning surface in a longitudinal direction;

a lateral subsystem for moving said patient positioning surface in a lateral direction;

a tilt subsystem including a ball screw and rotary nut for tilting said patient positioning surface;

a rotation subsystem for rotating said patient positioning surface; and

a control subsystem for controlling operation of said patient positioning system,

wherein said longitudinal subsystem moves said patient positioning surface in a longitudinal direction using a two-stage synchronized telescopic longitudinal system.

5. (Original) The system of claim 1, wherein said longitudinal subsystem and said lateral subsystem allow manual movement of said patient positioning surface in at least one of a lateral direction and a longitudinal direction.

6. (Previously presented) The system of claim 1, further comprising a base for securing said patient positioning system, said base affixed to a floor.

7. (Original) The system of claim 1, further comprising patient restraints for securing said patient to said patient positioning surface.

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8. (Previously presented) A patient positioning system for medical applications, said system comprising:

- a patient positioning surface for supporting a patient;
 - a lift subsystem for adjusting elevation of said patient positioning surface;
 - a longitudinal subsystem for moving said patient positioning surface in a longitudinal direction;
 - a lateral subsystem for moving said patient positioning surface in a lateral direction;
 - a tilt subsystem for tilting said patient positioning surface;
 - a rotation subsystem for rotating said patient positioning surface;
 - a control subsystem for controlling operation of said patient positioning system;
 - a power-on brake for braking when a voltage is supplied to said power-on brake;
- and
- a power-off brake for braking when a voltage is removed from said power-off brake.

9. (Original) The system of claim 1, further comprising at least one encoder for determining the position of said patient positioning surface.

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10. (Original) The system of claim 9, wherein said at least one encoder allows said patient positioning surface to return to a recorded position.

11. (Currently amended) A method for positioning a patient for medical applications, said method comprising:

vertically positioning a patient positioning surface to a desired height to allow a patient to be loaded onto the patient positioning surface;

rotating the patient positioning surface to a position to allow a patient to be loaded onto the patient positioning surface;

loading a patient on the patient positioning surface;

positioning the patient for a medical procedure, said positioning step comprising at least one of rotating, lifting, lateral motion, longitudinal motion, and longitudinal tilting of the patient positioning surface; **[[and]]**

maintaining a region of interest of the patient by tilting the patient positioning surface during a procedure involving movement of the patient positioning surface; **and**

returning the patient positioning surface to a horizontal starting position for emergency situations.

12. (Currently amended) A method for positioning a patient for medical applications, said method comprising:

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vertically positioning a patient positioning surface to a desired height to allow a patient to be loaded onto the patient positioning surface;

rotating the patient positioning surface to a position to allow a patient to be loaded onto the patient positioning surface;

loading a patient on the patient positioning surface;

positioning the patient for a medical procedure, said positioning step comprising at least one of rotating, lifting, lateral motion, longitudinal motion, and longitudinal tilting of the patient positioning surface;

maintaining a region of interest of the patient by tilting the patient positioning surface using a ball screw and rotary nut during movement of the patient positioning surface; and

unloading the patient from the patient positioning surface.

13. (Canceled)

14. (Original) The method of claim 11, further comprising securing the patient to the patient positioning surface.

15. (Original) The method of claim 11, further comprising locking the patient positioning surface during the medical procedure.

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16. (Original) The method of claim 11, further comprising manually moving the patient positioning surface in at least one of the lateral and longitudinal directions.

17. (Previously presented) A grouted tilting patient positioning system for vascular applications, said system comprising:

- a base for securing said patient positioning system, said base affixed to a floor;
- a patient positioning surface for supporting a patient;
- a telescopic lift subsystem for adjusting elevation of said patient positioning surface;
- a telescopic longitudinal subsystem including a rack and pinion mechanism for moving said patient positioning surface in a longitudinal direction;
- a lateral subsystem for moving said patient positioning surface in a lateral direction;
- a tilt subsystem including a ball screw and rotary nut for tilting said patient positioning surface; and
- a rotation subsystem for rotating said patient positioning surface.

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18. (Original) The system of claim 17, further comprising patient restraints for securing said patient to said patient positioning surface.

19. (Previously presented) A grouted tilting patient positioning system for vascular applications, said system comprising:

a base for securing said patient positioning system, said base affixed to a floor;

a patient positioning surface for supporting a patient;

a telescopic lift subsystem for adjusting elevation of said patient positioning surface;

a telescopic longitudinal subsystem for moving said patient positioning surface in a longitudinal direction;

a lateral subsystem for moving said patient positioning surface in a lateral direction;

a tilt subsystem for tilting said patient positioning surface;

a rotation subsystem for rotating said patient positioning surface;

a power-on brake for braking when a voltage is supplied to said power-on brake;

and

a power-off brake for braking when a voltage is removed from said power-off brake.

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20. (Original) The system of claim 17, further comprising at least one encoder for determining the position of said patient positioning surface.

21. (Original) The system of claim 20, wherein said at least one encoder allows said patient positioning surface to return to a recorded position.

22. (Original) The system of claim 17, further comprising a control subsystem for controlling operation of said patient positioning system.

23. (Original) The system of claim 22, wherein said control subsystem performs iso-center tracking to maintain a region of interest of said patient in an image area during tilt

24. (Original) The system of claim 22, wherein said control subsystem avoids collision with at least one of the ground and a predetermined object by continuously monitoring coordinates of all axes of motion, calculating a clearance from said at least one of said ground and said predetermined object, and stopping motion of said patient positioning surface if said clearance is less than or equal to a specified safe limit.

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25. (Currently amended) A patient positioning system, said system **[[.]]** comprising:

a table for positioning a patient, said table capable of rotation, lift, and longitudinal motions, said table capable of longitudinal tilt using a ball screw and rotary nut, wherein a region of interest of said patient is maintained in an image area during tilt by tilting said table in an inverse kinematic relationship with one or more of lifting and longitudinal movements of said table;

a base attaching said table to a floor; and

a user interface for controlling movement of said table.

26. (Previously presented) The patient positioning system of claim 8, wherein said longitudinal subsystem includes a rack and pinion mechanism.

27. (Previously presented) The system of claim 8, wherein said longitudinal subsystem moves said patient positioning surface in a longitudinal direction using a two-stage synchronized telescopic longitudinal system.

28. (Previously presented) The system of claim 8, wherein said tilt subsystem includes a ball screw and rotary nut.

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29. (Previously presented) The system of claim 8, wherein said lift subsystem adjusts elevation of said patient positioning surface using a two-stage synchronized telescopic lift system.

30. (Previously presented) The system of claim 8, further comprising a base for securing said patient positioning system, said base affixed to a floor.

31. (Previously presented) The system of claim 8, further comprising patient restraints for securing said patient to said patient positioning surface.

32. (Previously presented) The system of claim 19, further comprising a control subsystem for controlling operation of said system.

33. (Previously presented) The system of claim 32, wherein said control subsystem performs iso-center tracking to maintain a region of interest of said patient in an image area during tilt.

34. (Previously presented) The system of claim 32, wherein said control subsystem avoids collision with at least one of the ground and a predetermined object by continuously monitoring coordinates of all axes of motion, calculating a

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clearance from said at least one of said ground and said predetermined object, and
stopping motion of said patient positioning surface if said clearance is less than or equal
to a specified safe limit.

35. (Previously presented) The system of claim 19, further comprising
at least one encoder for determining the position of said patient positioning surface.

36. (Previously presented) The system of claim 35, wherein said at
least one encoder allows said patient positioning surface to return to a recorded position.